Model Numbering System

17	H	D	0	0	01	-	01
a	b	c	d	e	f		g

a **Frame Size**
motor outside diameter in tenths of an inch (example: size 17 = 1.7”)

b **Type of Stepping Motor**
“H” means Hybrid Stepping Motor

c **Type of Step Angle**
A/K: step angle 0.9°, stator: 8 polar
C: step angle 1.2°
D: step angle 1.8°, stator: 8 polar, teeth distributing asymmetrically
E: step angle 3.6°, stator: 8 polar
F: step angle 3.75°, stator: 8 polar
S: step angle 1.8°, stator: 8 polar, large rotor
Y: step angle 1.8°, stator: 8 polar, small rotor

d **Stator Length**

e **Type of Lead Wires**
“0” indicates connector only, “4” “5” “6” “8” indicates number of lead wires

f **Electric Variation**
variety of current, torque, etc.

g **Mechanical Variation**
variety of shaft, lead wires, screws, etc.